

Rotation Motorized Stages Stage Size φ 40 mm / φ 60 mm

OSMS-YAW





Stepping motor driven rotation stages utilizing precision bearings and worm gear drive mechanisms.

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40 × 40 mm

60 × 60 mm 80 × 80 mm

85 × 85 mm

100 × 100 mm

120 × 120 mm

Others



 Suitable for rotating optics aout the optical axis, measuring, inspection and evaluation instruments.

• 360° continuous motion

Low, compact profile
 Adapters to hold a variety of optics are available.

Guide

▶ Rotation Range Minus limit sensor: -2.5° Scale: 0°

Clockwise CW direction Stops at near 0° (-2.5°)

- ▶ Homing of rotation motorized stages is performed using the CW limit sensor as the origin sensor.
- ▶ Origin detection is adjusted so that the stage stops at 0 degrees when homing is performed in the MINI system at half step.

Attention

▶ Load capacity and precision may be derated when mounted upside down or vertically. Contact us for informations regarding your specific application.

Specification	ons				
Part Number		OSMS-40YAW	OSMS-60YAW	OSMS-60YAW-W	
	Rotation Range		Move in the counterclockwise CCW of	lirection to ∞, and stop at near 0 degree	e (-2.5°) in the clockwise CW direction
	Stage Size	[mm]	φ40	φ60	φ60
Mechanical Specifications	Travel Mech (reduction ra		Worm gear (1:144)	Worm gear (1:144)	Worm gear (1:144)
Specifications	Positioning	Slide	Bearing method	Bearing method	Bearing method
	Stage Mate	rial	Aluminum / Aluminum bronze	Aluminum / Aluminum bronze	Aluminum / Aluminum bronze
	Weight [kg]		0.35	0.45	1.0
	Resolution	(Full) [°/pulse]	0.005	0.005	0.005
	Resolution	(Half) [°/pulse]	0.0025	0.0025	0.0025
	MAX Speed [°/sec]		30	30	30
	Positioning	Accuracy [°]	0.1	0.1	_
	Positional Repeatability [°]		0.02	0.02	0.02
Accuracy	Load Capacity [N]		19.6 (2.0kgf)	29.4 (3.0kgf)	29.4 (3.0kgf)
Specifications	Moment Stiffness ["/N·cm]		2	1	_
	Lost Motion [°]		0.05	0.05	0.05
	Backlash [°	']	0.1	0.1	0.1
	Parallelism	[µm]	50	50	_
	Concentrici	ty [µm]	30	30	_
	Wobble [mm]		0.02	0.02	-
	Sensor Part Number		Micro Photoelectric Sensor: PM-F25 (SUNX Co., Ltd.)	Micro Photoelectric Sensor: PM-R25 (SUNX Co., Ltd.)	Micro Photoelectric Sensor: PM-R25 (SUNX Co., Ltd.)
Sensor	Limit Senso	r	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
	Origin Sens	or	None	None	None
	Proximity O	rigin Sensor	None	None	None

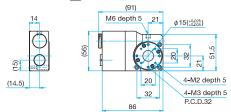
Motor / Se	Motor / Sensor Specifications		
	Туре	5-phase stepping motor 0.75A/phase (Tamagawa Seiki Co., Ltd.)	
Motor	Motor Part Number	TS3664N4E10 (□24mm)	
	Step Angle	0.72°	
	Power Voltage	DC5 - 24V ±10%	
0	Current Consumption	15mA or lower	
Sensor	Control Output	NPN open collector output DC30V or lower, 50mA or lower	
	Output Logic	When shaded: Output transistor OFF (no conduction)	

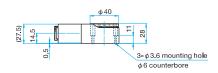
Compatible Driver / Controller		
Control System	Compatible Driver	SG-5M, SG-5MA, MC-S0514ZU, SG-514MSC, MC-7514PCL
Control System	Compatible Controller	GSC-01, GSC-02, SHOT-702, GIP-101, HSC-103, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04-U

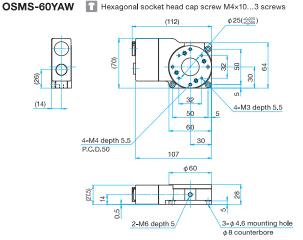


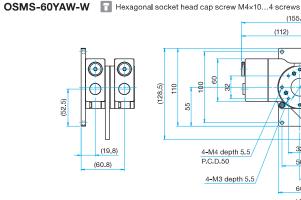


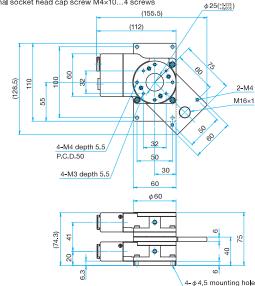
Outline Drawing





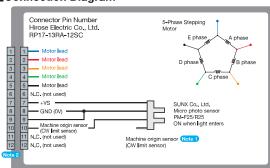








■Connection Diagram



When a travel command in the "+" direction is issued, the mounting table rotates to ∞ in the CCW (counterclockwise) direction viewed from the top surface, but it is stopped by the town contensor when the machine origin is ensory (I Wimit sensor) in the CW (clockwise) direction.

Detect the machine origin using the method (MINI system) that detects the origin with a machine origin sensor (CW limit sensor).

Note 2 Compatible cable connector: Hirose Electric Co., Ltd. RP17-13PA-12PC/RP17-PC-122

■ Machine Origin Detection

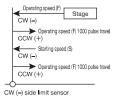
MINI System

When the machine origin detection command is when the machine origin detection command is issued, the stage starts travelling in the CW (-) direction at the operating speed (F) set with the memory switch, and stops by the CW (-) side limit sensor. Then it travels in the CCW (+) direction at the operating speed (F) for 1000 pulses.

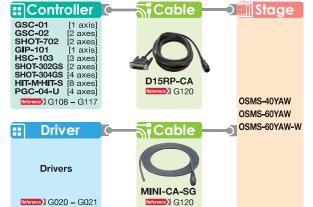
After stop, it starts travelling in the CW (-) and direction areain at the starting speed (S) and

After stop, it starts traveling in the CW (-) direction again at the starting speed (5), and stops by the CW (-) side limit sensor. After that, it travels in the CCW (+) direction at the operating speed (F) for 1000 pulses.

This position is regarded as the machine origin.



■Compatible Controllers / Drivers and Cables



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40 × 40 mm 60 × 60 mm

80 × 80 mm 85 × 85 mm

100 × 100 mm

120 × 120 mm



Rotation Motorized Stages Stage Size φ 80 mm / φ 120 mm / φ 160 mm

OSMS-YAW





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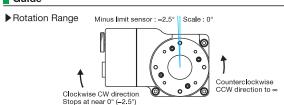
120 × 120 mm

Others



- Suitable for rotating optics aout the optical axis, measuring, inspection and evaluation instruments.
- 360° continuous motion
- Low, compact profile
 Adapters to hold a variety of optics are available.

Guide



- ▶ Homing of rotation motorized stages is performed using the CW limit sensor as the origin sensor.
- ▶ Origin detection is adjusted so that the stage stops at 0 degrees when homing is performed in the MINI system at half step.

Attention

▶ Load capacity and precision may be derated when mounted upside down or vertically. Contact us for informations regarding your specific application.

Specifications						
Part Number	Part Number		OSMS-80YAW	OSMS-120YAW	OSMS-160YAW	OSMS-120YAW-W
	Rotation Ra	ınge	Move in the counterclockwis	se CCW direction to ∞, and st	op at near 0 degree (-2.5°) ir	the clockwise CW direction.
	Stage Size	[mm]	φ80	φ120	φ160	φ120
Mechanical	Travel Mech (reduction r		Worm gear (1:144)	Worm gear (1:144)	Worm gear (1:144)	Worm gear (1:144)
Specifications	Positioning	Slide	Bearing method	Crossed roller	Crossed roller	Crossed roller
	Stage Mate	rial	Aluminum / Aluminum bronze	Aluminum / Aluminum bronze	Aluminum / Aluminum bronze	Aluminum / Aluminum bronze
	Weight [kg]		1.1	2.0	2.5	5.5
	Resolution	(Full) [°/pulse]	0.005	0.005	0.005	0.005
	Resolution	(Half) [°/pulse]	0.0025	0.0025	0.0025	0.0025
	MAX Speed [°/sec]		30	30	30	30
	Positioning	Accuracy [°]	0.15	0.1	0.1	_
	Positional Repeatability [°]		0.02	0.02	0.02	0.02
Accuracy	Load Capacity [N]		98 (10.0kgf)	196 (20.0kgf)	196 (20.0kgf)	196 (20.0kgf)
Specifications	Moment Stiffness ["/N+cm]		0.2	0.1	0.1	_
	Lost Motion [°]		0.05	0.05	0.05	_
	Backlash [°	,]	0.08	0.08	0.08	0.08
	Parallelism	[µm]	50	50	60	_
	Concentrici	ty [µm]	30	30	30	_
	Wobble [mm]		0.02	0.02	0.02	_
	Sensor Part	Number		Micro Photoelectric Senso	r: PM-F25 (SUNX Co., Ltd.)	
0	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
Sensor	Origin Sens	or	None	None	None	None
	Proximity O	rigin Sensor	None	None	None	None

Motor / Sensor Specifications		
	Туре	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)
Motor	Motor Part Number	PK525HPB-C4 (□28mm)
	Step Angle	0.72°
Sensor	Power Voltage	DC5 – 24V ±10%
	Current Consumption	15mA or lower
	Control Output	NPN open collector output DC30V or lower, 50mA or lower
	Output Logic	When shaded: Output transistor OFF (no conduction)

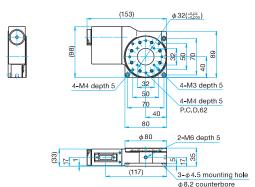
Compatible Driver / Controller		
Control System	Compatible Driver	MC-S0514ZU, SG-514MSC, MC-7514PCL
Control System	Compatible Controller	SHOT-702, HSC-103, GIP-101, SHOT-302GS, SHOT-304GS, HIT-M·HIT-S, PGC-04-U

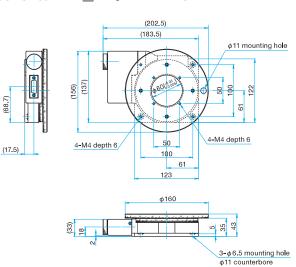




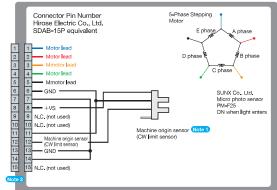
Outline Drawing

OSMS-80YAW Thexagonal socket head cap screw M4×10...3 screws





■Connection Diagram



When a travel command in the "+" direction is issued, the mounting table rotates to ∞ in the CCW (counterclockwise) direction viewed from the top surface, but it is stopped by the machine origin sensor (CW limit sensor) in the CW (clockwise) direction. Detect the machine origin using the method (MINI system) that detects the origin with a machine origin sensor (CW limit sensor).

Note 2 Compatible cable connector: DDK Ltd. 17JE-13150

■ Machine Origin Detection

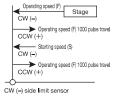
MINI System

When the machine origin detection command is when the machine origin detection command is issued, the stage starts travelling in the CW (-) direction at the operating speed (F) set with the memory switch, and stops by the CW (-) side limit sensor. Then it travels in the CCW (+) direction at the operating speed (F) for 1000 pulses.

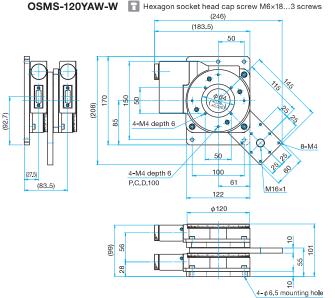
After stop, it starts travelling in the CW (-) and direction areain at the starting speed (S) and

After stop, it starts traveling in the CW-() direction again at the starting speed (5), and stops by the CW (-) side limit sensor. After that, it travels in the CCW (+) direction at the operating speed (F) for 1000 pulses.

This position is regarded as the machine origin.

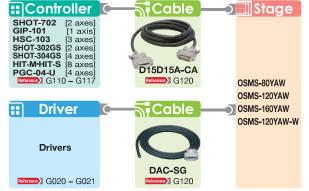


(183.5)(137) 50 22 58 4-M4 depth 6 50 4-M4 depth 6 100 61 P.C.D.100 123 φ120 35 3-φ6.5 mounting hole φ11 counterbore





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40 × 40 mm

60 × 60 mm 80 × 80 mm

85 × 85 mm

100 × 100 mm

120 × 120 mm



Precision Rotation Motorized Stages





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40 × 40 mm

60 × 60 mm

80 × 80 mm

85 × 85 mm

100 x 100 mm

120 × 120 mm

Others

Stage Size φ 120 mm / φ 160 mm

High precision and high stability rotation motorized stages fitted with bearing positioning slide. The combination of HST Series and 3 axis Stage Controllers HSC-103 can perform low-noise and low-vibration operation, compared with conventional products.



• Rotation motorized stages suitable for use when high load capacity is required.

Guide

▶ Rotation Range

- ▶ Homing of rotation motorized stages is performed using the CW limit sensor as the origin sensor.
- ▶ Origin detection is adjusted so that the stage stops at 0 degrees when homing is performed in the MINI system at half step.

Attention

 \blacktriangleright Load capacity and precision may be derated when mounted upside down or vertically. Contact us for informations regarding your specific application.

Part Number	Part Number		HST-120YAW-0B	HST-160YAW-0B
	Rotation Ra	ınge	Move in the counterclockwise CCW direction to ∞, and sto	op at near 0 degree (-2.5°) in the clockwise CW direction
	Stage Size	[mm]	φ120	φ160
Mechanical	Travel Mech (reduction r		Worm gear (1:144)	Worm gear (1:144)
Specifications	Positioning	Slide	Bearing method	Bearing method
	Stage Mate	rial	Aluminum / Aluminum bronze	Aluminum / Aluminum bronze
	Weight [kg]		5	8.5
	Deschales	(Full) [°/pulse]	0.005	0.005
	Resolution	(Half) [°/pulse]	0.0025	0.0025
	MAX Speed	f [°/sec]	30	30
	Positioning	Accuracy [°]	0.1	0.1
	Positional Repeatability [°]		0.01	0.01
Accuracy	Load Capacity [N]		343 (35.0kgf)	392 (40 . 0kgf)
Specifications	Moment Stiffness ["/N+cm]		0.015	0.01
	Lost Motion [°]		0.01	0.01
	Backlash [°]		0.003	0.003
	Parallelism	[µm]	50	50
	Concentrici	ty [µm]	20	20
	Wobble [mm]		0.01	0.01
	Sensor Parl	Number	Micro Photoelectric Sensor: PM-U25 (SUNX Co., Ltd.)	Micro Photo Sensor: PM-F25 (SUNX Co., Ltd.)
Sensor	Limit Senso	or	Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
Sensor	Origin Sens	or	None	None
	Proximity O	rigin Sensor	None	None

Motor / S	Motor / Sensor Specifications		
	Туре	5-phase stepping motor 1.4A/phase (Oriental Motor Co., Ltd.)	
Motor	Motor Part Number	PKP546N18B (□42mm)	
	Step Angle	0.72°	
	Power Voltage	DC5 – 24V ±10%	
Sensor	Current Consumption	15mA or lower	
Serisor	Control Output	NPN open collector output DC30V or lower, 50mA or lower	
	Output Logic	When shaded: Output transistor OFF	

Compatible Cable		
Cable	Driver Cable	D15D15A-CA

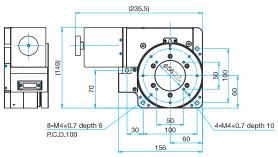
Compatible Driver / Controller		
Control System -	Compatible Driver	SG-5M*, MC-S0514ZU, SG-514MSC*, MC-7514PCL (* DC36V)
	Compatible Controller	HSC-103, SHOT-302GS, SHOT-304GS, HIT-M·HIT-SH, PGC-04-U

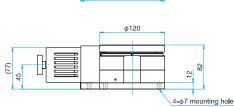


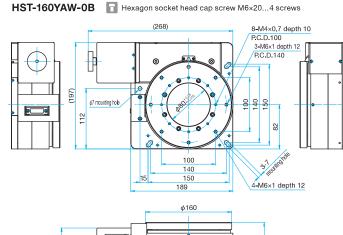


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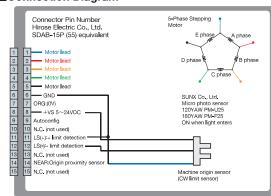
Outline Drawing







■Connection Diagram



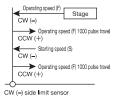
■ Machine Origin Detection

MINI System

MINI System
When the machine origin detection command is issued, the stage starts traveling in the CW (-) direction at the operating speed (F) set with the memory switch, and stops by the CW (-) side limit sensor. Then it travels in the CCW (+) direction at the operating speed (F) for 1000 pulses.
After stop, it starts traveling in the CW (-) and direction again at the starting speed (S) and

After stop, it starts traveling in the CW-() direction again at the starting speed (5), and stops by the CW (-) side limit sensor. After that, it travels in the CCW (+) direction at the operating speed (F) for 1000 pulses.

This position is regarded as the machine origin.



■Compatible Controllers / Drivers and Cables



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80 × 80 mm 85 × 85 mm

100 × 100 mm

120 × 120 mm



High Durability Motorized Rotation Stages Stage Size φ 60 mm / φ 80 mm / φ 120 mm

HDS-YAW





Limited range high duty cycle rotation stage.

• Good for the automatic alignment devices which need to repeatedly adjust the angle of rotation by a small amount.

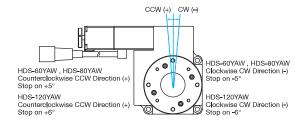
The ball screw system drive mechanism reduces abrasion and backlash for high durability.

• Since it converts linear motion of the ball screw into rotational motion using a steel belt, the angular spped and resolution is the same over the full range of travel.



Guide

▶ The origin sensor for HDS series is at the center of travel (0°).



Attention

▶ The HDS series should always be mounted horizontally. Performance can not be guaranteed if used in other orientations. If other oritnations are required, please contact our Sales Division.

Specifications HDS-60YAW HDS-80YAW HDS-120YAW Part Number Rotation Range ±6° ±5° ±5° Stage Size [mm] φ80 φ120 φ60 Ball screw with steel belt Ball screw with steel belt Travel Mechanism Ball screw with steel belt Mechanical Crossed roller guide Positioning Slide Bearing method Bearing method Specifications Stage Material Aluminum Aluminum Aluminum Finish Black anodized Black anodized Black anodized Weight [kg] 0.5 0.9 1.4 (Full) [°/pulse] ÷0.0053 **≑**0.0038 ÷0.0022 Resolution (Half) [°/pulse] **=**0.0027 **≑**0.0019 **≑**0.0011 MAX Speed [°/sec] 60 60 60 Positioning Accuracy [°] 0.05 0.05 0.05 Positional Repeatability [°] 0.003 0.003 0.003 Load Capacity [N] 29.4 (3.0kgf) 58.8 (3.0kgf) 98 (10kgf) Accuracy Specifications Moment Stiffness ["/N·cm] 1 0.2 0.1 0.003 0.003 0.003 Lost Motion [°] 0.05 0.05 0.05 Backlash [°] Parallelism [µm] 50 50 50 Concentricity [µm] 10 10 Wobble [mm] 0.01 0.01 Sensor Part Number Micro photo sensor: GP1S097HCZ(Sharp Corporation) Limit Sensor Equipped (NORMAL CLOSE) Equipped (NORMAL CLOSE) Equipped (NORMAL CLOSE) Sensor Equipped (NORMAL OPEN) Equipped (NORMAL OPEN) Equipped (NORMAL OPEN) Origin Sensor Proximity Origin Sensor None None None

Motor / Sensor Specifications				
	Туре	5-phase stepping motor 0.75A/phase (Tamagawa Seiki Co., Ltd.)	5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.)	
Motor	Motor Part Number	TS3664N4E10 (□24mm)	PK523HPB-C12 (□28mm)	
	Step Angle		0.72°	
	Power Voltage	DC5 - 24V±10%		
	Current Consumption	60mA or lower (20mA per sensor)		
Sensor	Control Output	NPN open	collector output DC30V or lower, 50mA or lower	
	Output Logic	When shaded: Output transistor OFF (no conduction): Limit sensor When shaded: Output transistor ON (conduction): Origin sensor		

Compatible Driver / Controller			
Control System	Compatible Driver	SG-5M, SG-5MA, SG-55M, MC-S0514ZU, MC-7514PCL	
Control System	Compatible Controller	GSC-01, GIP-101, GSC-02, SHOT-702, HSC-103, SHOT-302GS, SHOT-304GS, HIT-M+HIT-S, PGC-04-U	

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Vacuum Options

40 × 40 mm

60 × 60 mm

80 × 80 mm

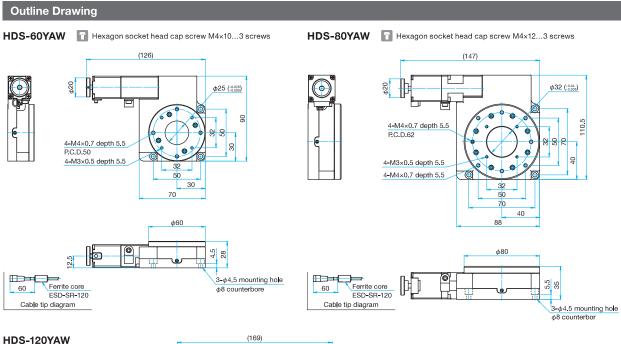
85 × 85 mm

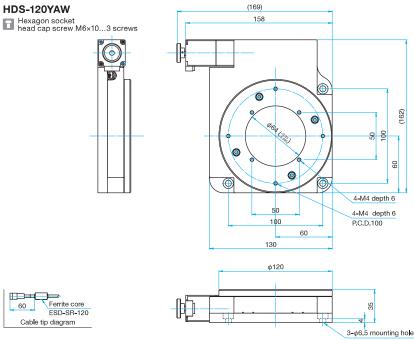
100 × 100 mm

120 × 120 mm

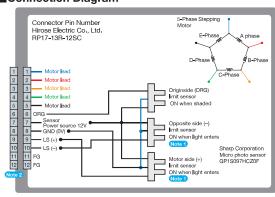








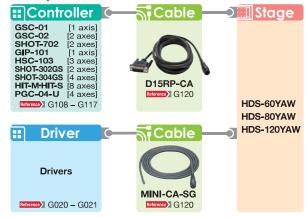
■Connection Diagram



Note 1 The motor side limit sensor is the (+) forward direction limit sensor.

Note 2 Compatible cable connector:
Hirose Electric Co., Ltd. RP17-13PA-12PC/RP17-PC-122

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